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For controlling these parts as illustrated in the movement phases according to Figs. 3 to 5, the control lever 37 of the control device 31 is guided in a slotted hole 44 of the control disk 41 by means of a joint bolt 45. In this connection, the control disk 41 is secured by means of a tension spring 34 engaging above the slotted hole 44 in a permanent nominal position on the control lever 37 until the movement lock becomes effective. At the same time, the parts are tensioned relative to one another as well as relative to the frame in the area of the hinge device 7 in that between the control device 31 and the two hinge lifters 21, 21' the two leaf springs 32, 33 ~~31, 33~~ that extend between the upper transverse axis 38 and the lower stop shaft 43 rest with their double-arc-shaped ends 50, 50' on the stop shaft 43 and the transverse axis 36, respectively. In this way, the stop shaft 43 is secured by a spring force in its position of use in which it engages with cylindrical stop cam 46 from below the profiled clamping section in the area between the legs T' and T'' of the frame part T.

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The hinge device 7 is provided in the area of the movement lock 30 with an emergency release which in the illustrated embodiment is provided in the area of the stop shaft 43. As an emergency release, on the stop shaft 43 (Fig. 6) at least one manual lever 48 (and 48' on the other side) is provided that can be pivoted against the tensioning force of the leaf springs 32, 33 ~~31, 33~~. This release possibility (arrow S') is achieved in that the leaf springs 32 and 33 on both sides of the cylindrical stop cam 46 provided for the central control disk 41 are supported on the stop shaft 43 by means of a cam part 49, 49' (Fig. 5) that extends eccentrically to the longitudinal axis S of the stop shaft 43 and is thus eccentrically shaped, respectively.